Large scale density estimation of blue and fin whales: combined distribution and density estimates using bearing data.



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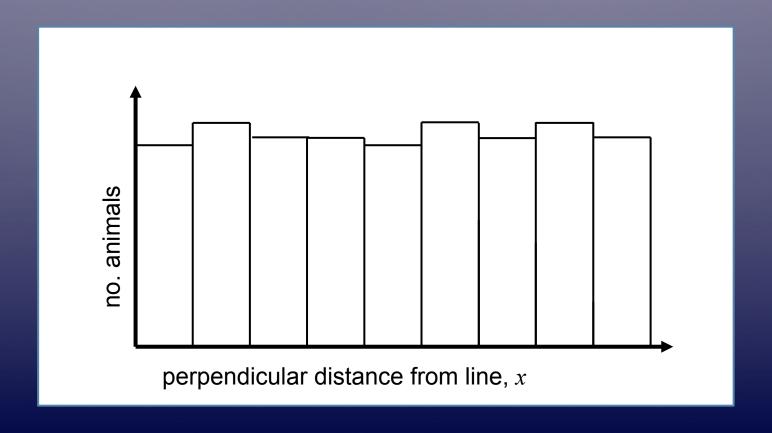
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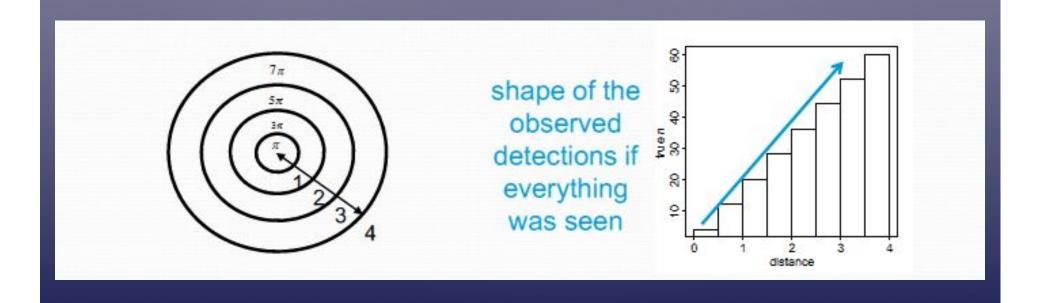
Large Scale Density Estimation Project

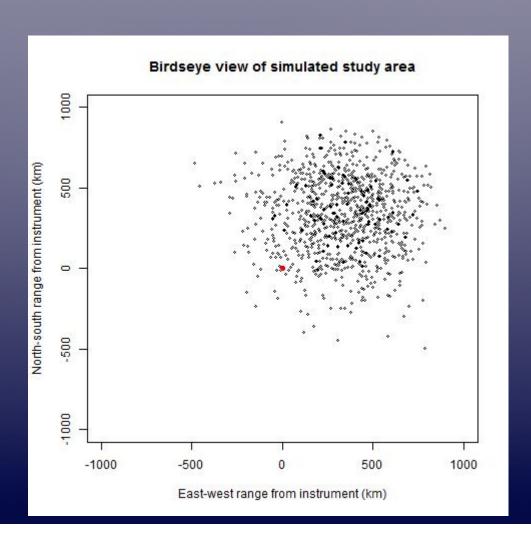
- ONR funded project
- **Goa**l: develop new density estimation method using bearing information from sparse arrays
- Will:
- (a) be effective over large spatial scales.
- (b) be designed to cope with spatial variation in animal density
- (c) utilize sparse array data.
- Target species: developed for blue and fin whales but will be directly applicable to other species

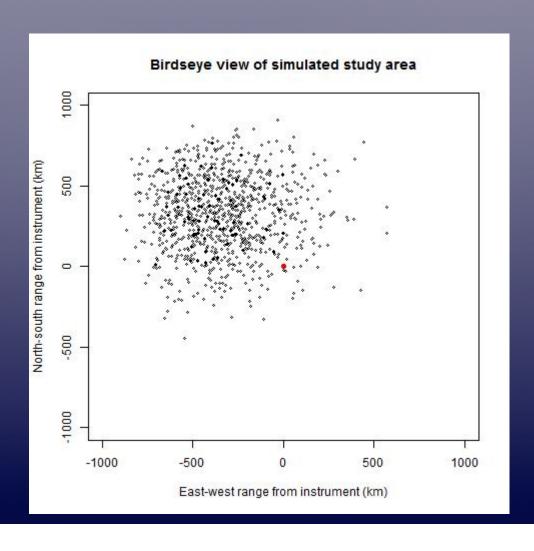
Key assumptions of standard density estimation methods
 on average, animal distribution with respect to the monitoring lines is uniform.

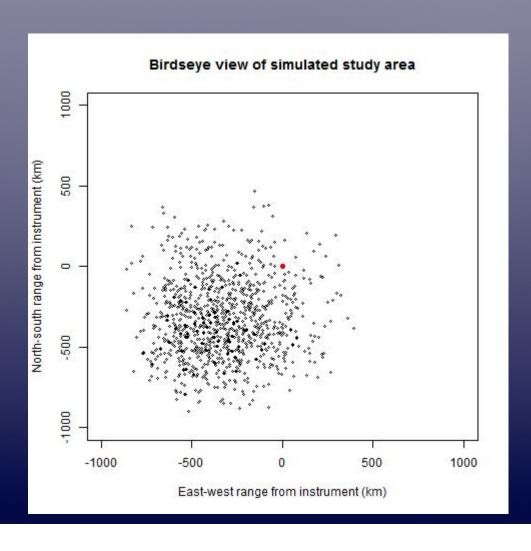


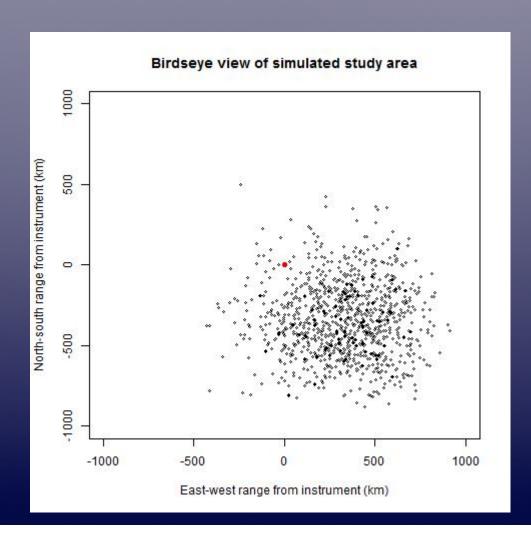
Key assumptions of standard density estimation methods
 on average, animal distribution with respect to the monitoring points is triangular.

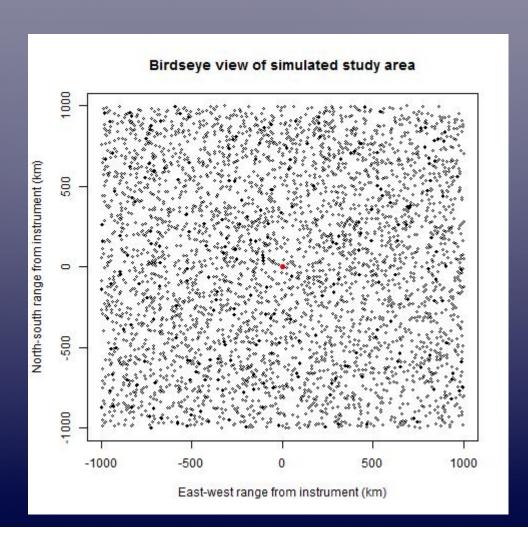




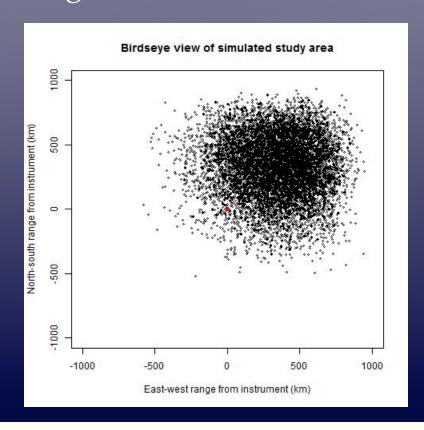




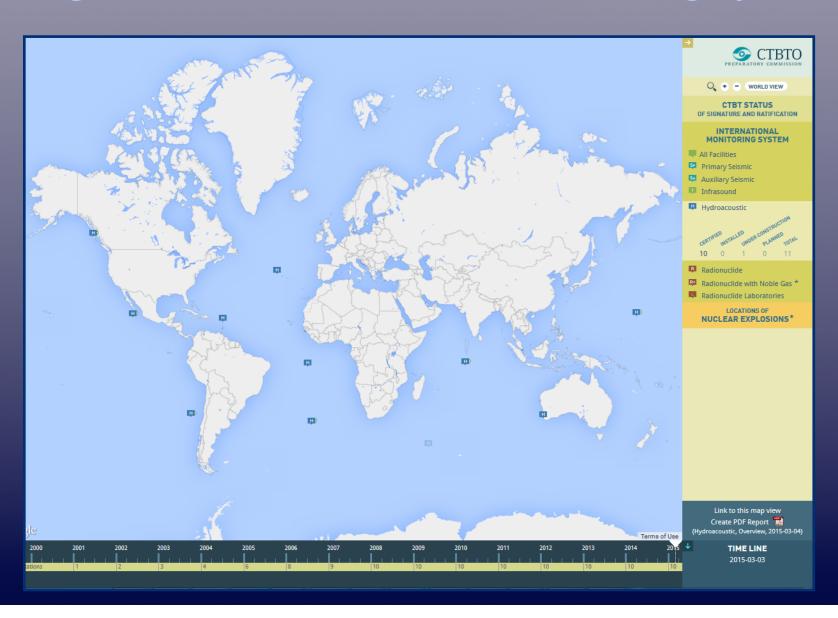




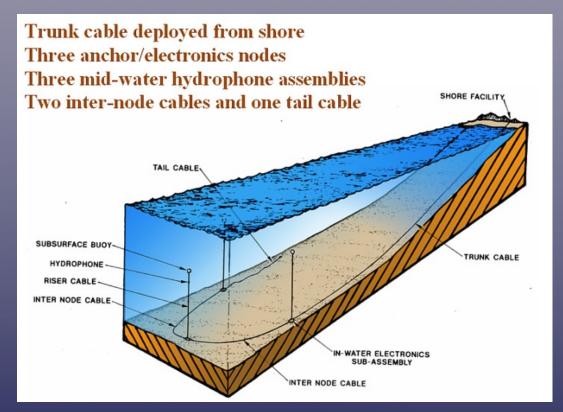
- With few monitoring lines/points, assumption likely to be violated.
- This is the case for sparse arrays particularly if monitoring a large area.



Comprehensive Nuclear Test Ban Treaty Organisation: International Monitoring System



CTBTO Hydroacoustic Instruments

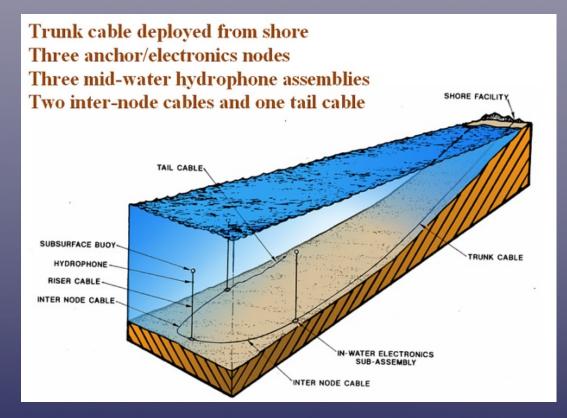


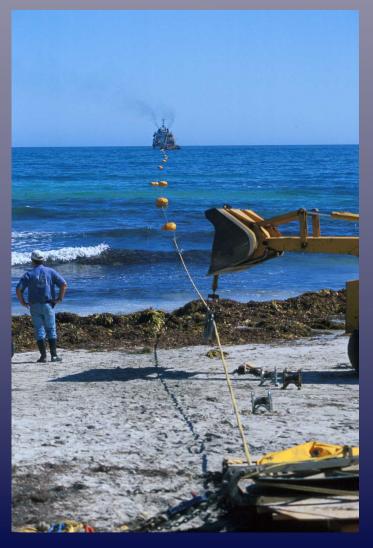




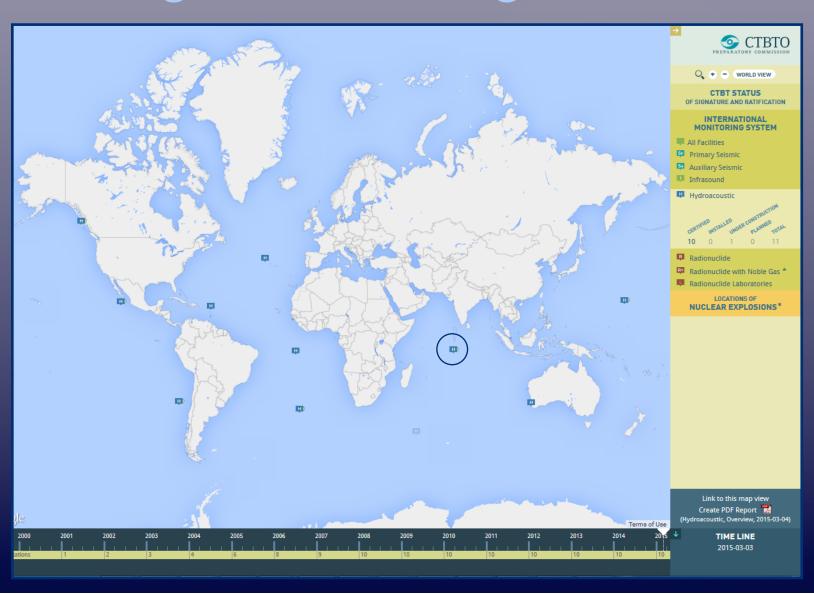
From 'CTBTO Public Information, http://www.ctbto.org/

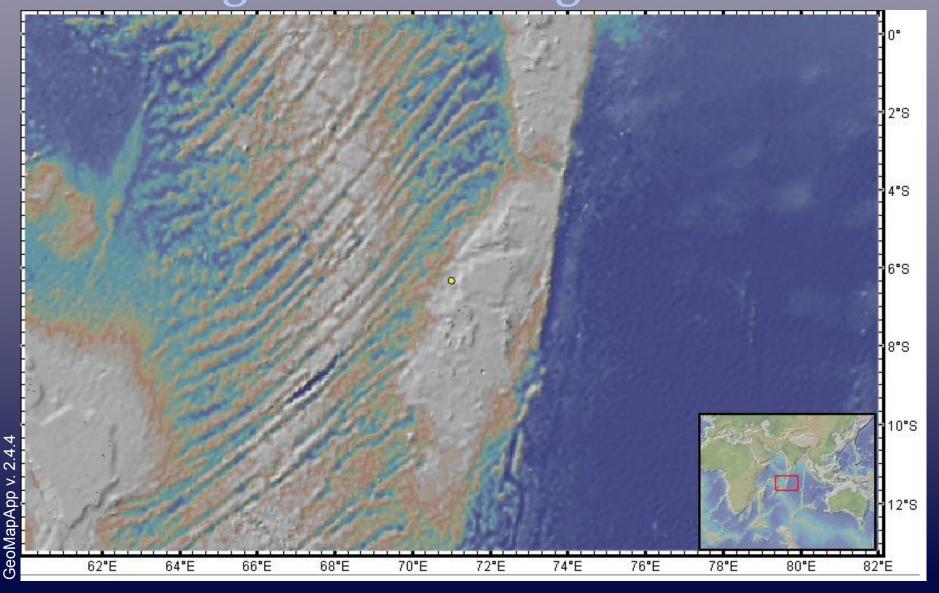
CTBTO Hydroacoustic Instruments

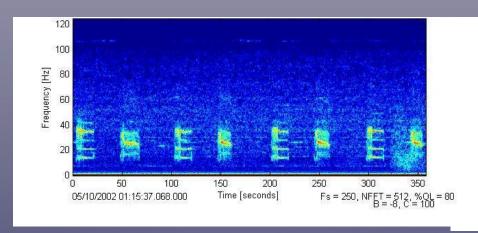


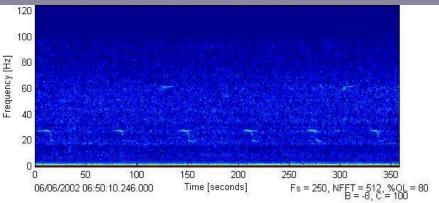


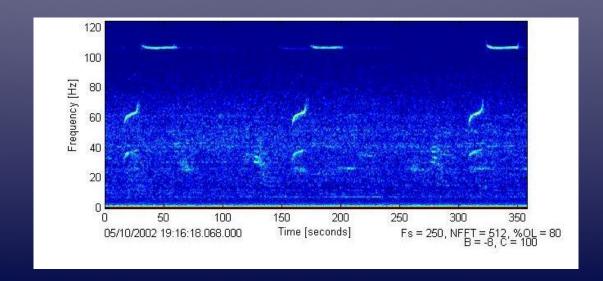
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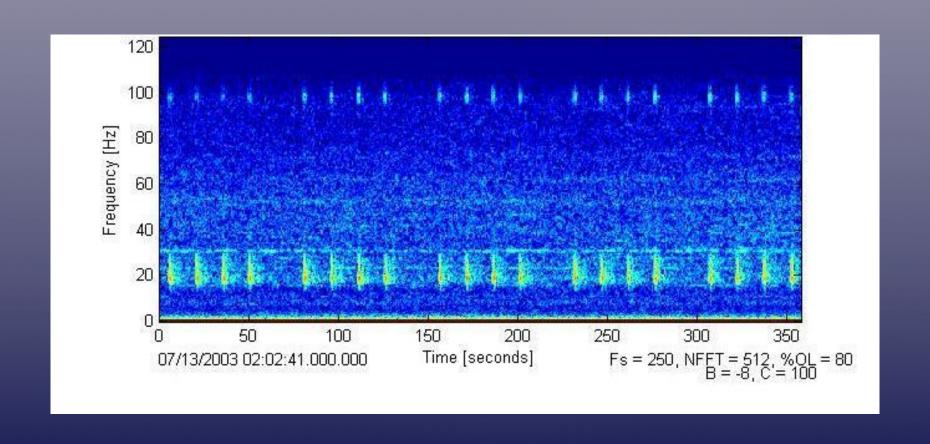












- For each detected call:
 - Horizontal bearing to calls
 - Call signal to noise ratio

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 - Source level information

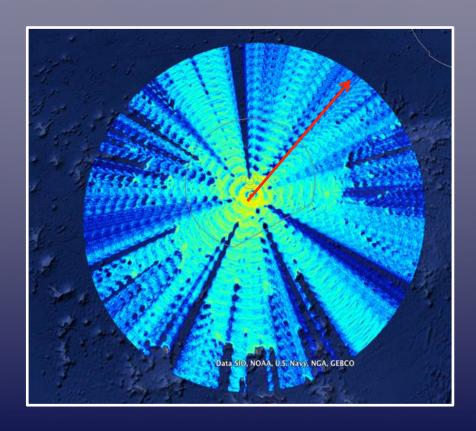
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- Characterised detector:
 - Linking detection probability to SNR

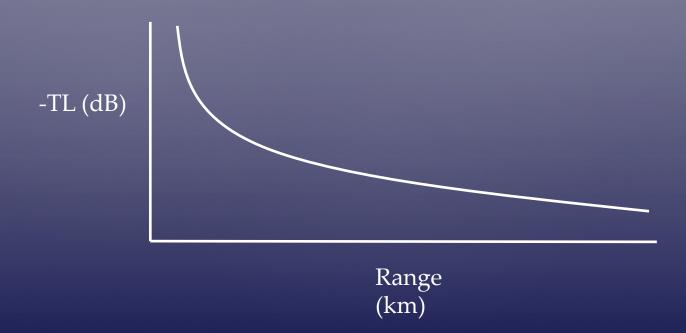
- For each detected call:
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- Characterised detector:
 - Linking detection probability to SNR
- Oceanography data:
 - Sound propagation
 - Noise levels (for simulation)

• Use bearing to assign bearing-specific transmission loss (TL) data to call



• Use call received level (RL) and TL to estimate source level (SL) at each range step



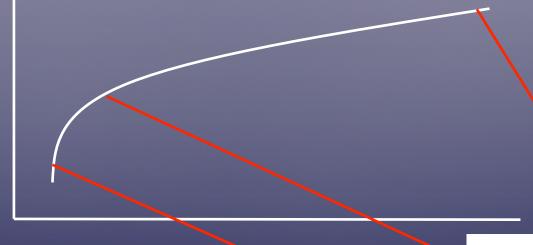
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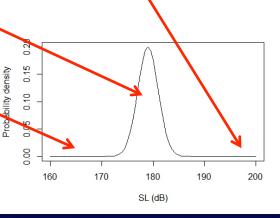
Predicted SL (dB)



• Assess the probability density of each predicted SL at each range using an assumed SL distribution.

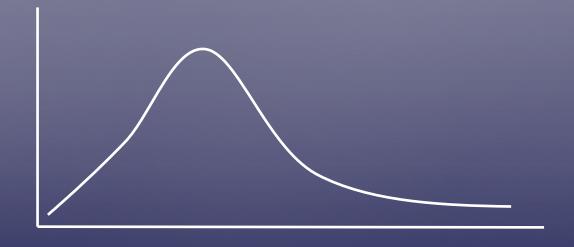
Predicted SL (dB)



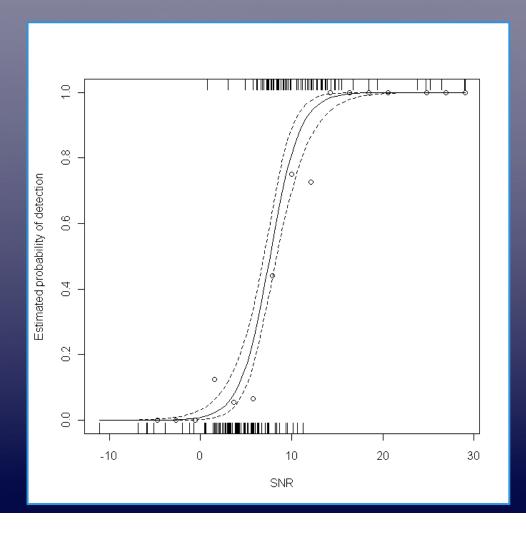


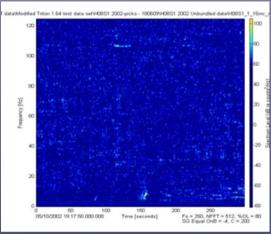
• Split the call along the range according to the weighting from the SL pdf.

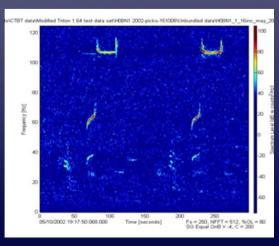
Proportion of a single call



• Correct the call for missed calls using relationship between signal to noise (SNR) and probability of detection.

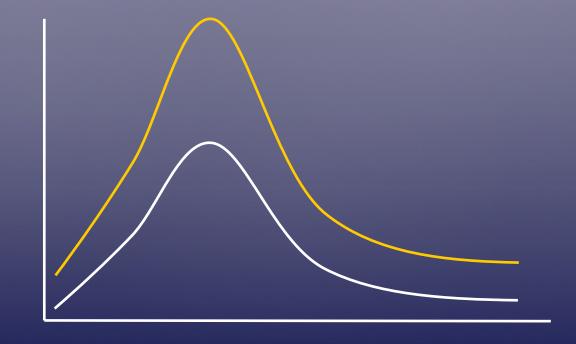




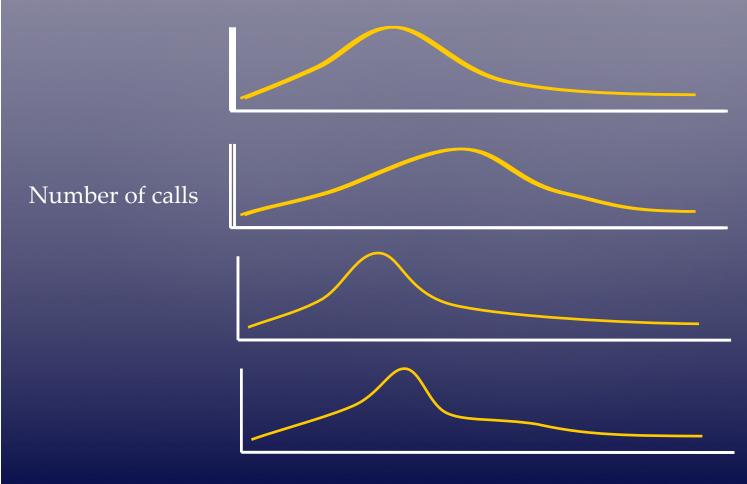


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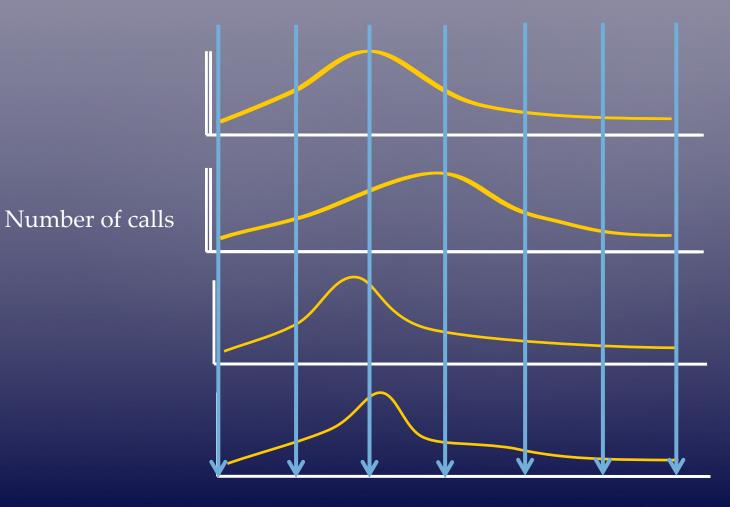
Single call corrected for missed calls



• Do this for all calls along the same bearing...



...and sum them across range bins



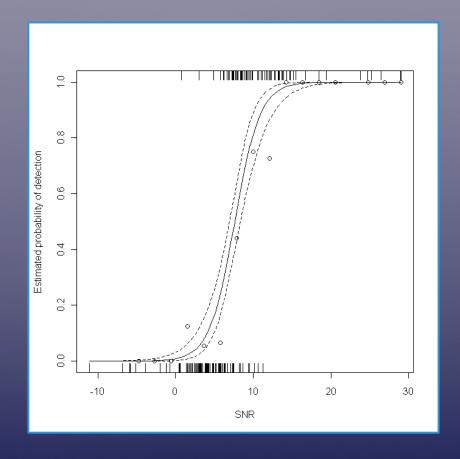
- The final step is to use the no. calls in each range bin across all bearings in a spatial model
- Generalised additive model with bearing and range as 2D smooth.

Simulation study - goals

- Assess the bias in estimated abundance
- For a range of scenarios

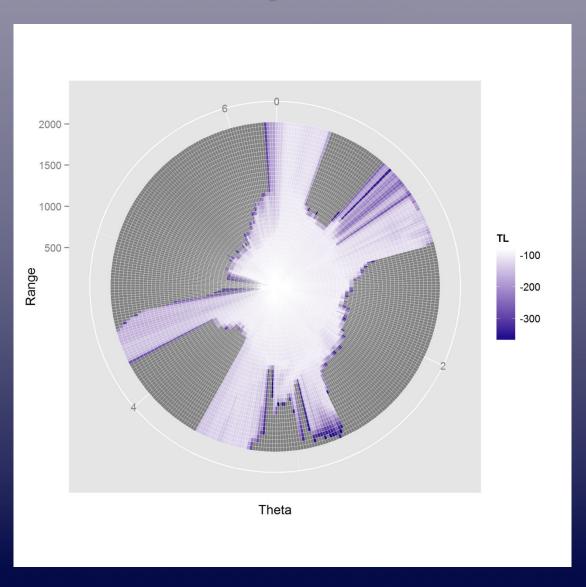
Simulation study - inputs

- Based on Sri Lankan blue whale calls (106 Hz at 30 m)
- SL data from literature (mean = 179 dB, sd = 2)*
- Detector characterisation from Harris (2012)
- TL model provided by K. Heaney, OASIS.
- NL data (mean = 175 dB, sd = 3.5) from Harris (2012)

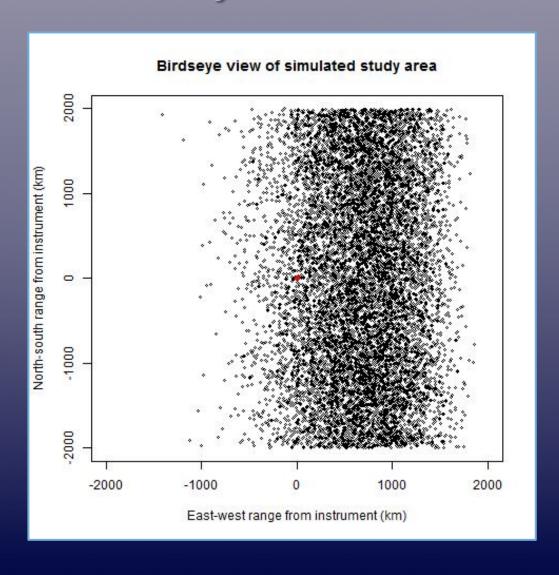


*from Gavrilov et al. (2011)

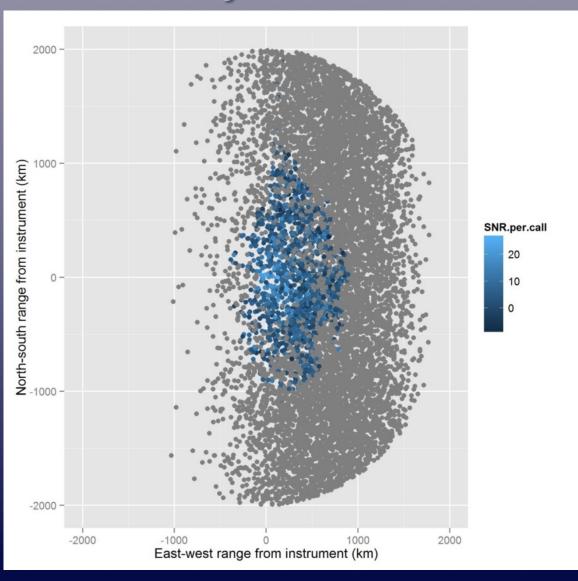
Simulation study - TL data



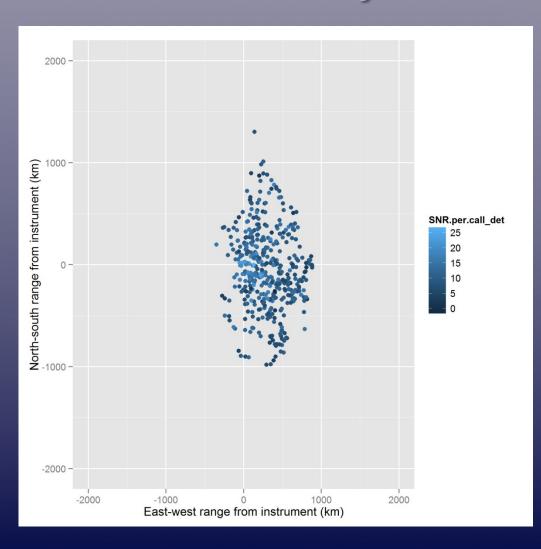
Simulation study – all simulated calls

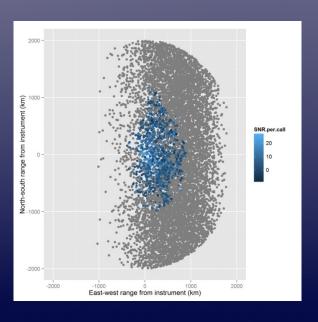


Simulation study – all simulated calls

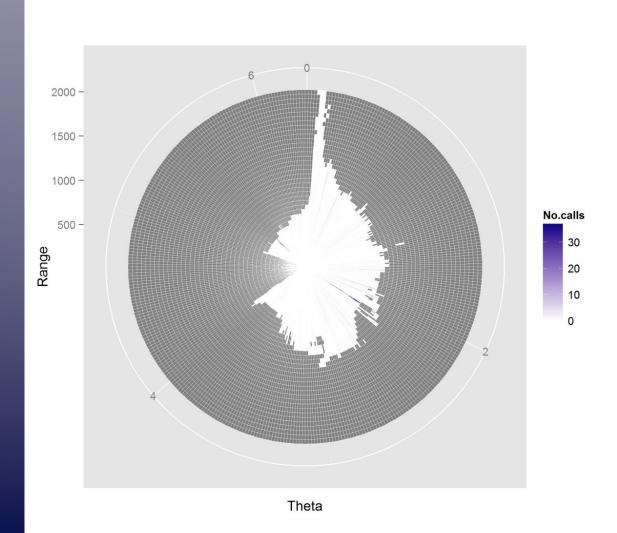


Simulation study – all simulated calls

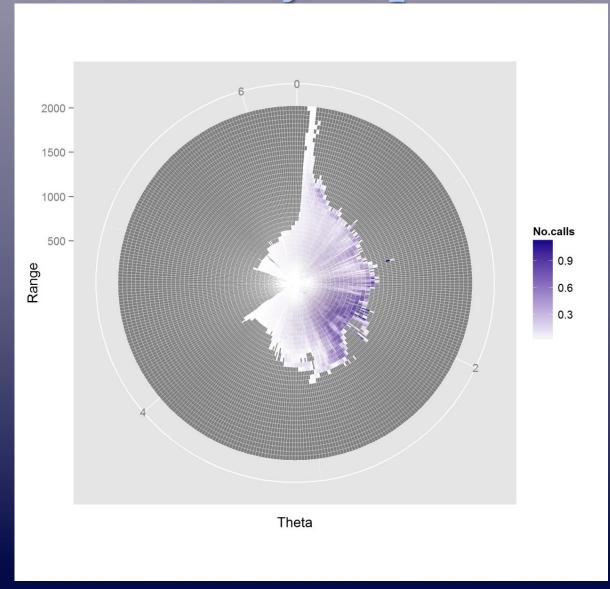




Simulation study – "split" calls



Simulation study – spatial model



Simulation study – results

- Based on 100 simulations.
- Median number of detections: 450 calls
- Mean TL level for non-detection: -101 dB
- Median bias: 7%

Simulation study – extensions

- Spatial model should account for spatial autocorrelation.
- Is it better to predict over a smaller range less bias?
- Source levels from data (possible from CTBT data).
- 2000 11000 11000 -

- Run more scenarios different distribution
- Compare with OBS system where ranging and distance sampling, a standard abundance estimation method, can be used.
- Call production rates required for animal density.

Acknowledgments

- Kevin Heaney at OASIS
- Mike Weise at the Office of Naval Research



Reference: Gavrilov, A. N., McCauley, R. D., Salgado-Kent, C., Tripovich, J., & Burton, C. (2011), Vocal characteristics of pygmy blue whales and their change over time. *Journal of the Acoustical Society of America*, 130(6), 3651-3660.